

**GUJARAT TECHNOLOGICAL UNIVERSITY****BE - SEMESTER VI- • EXAMINATION – SUMMER 2015****Subject Code: 160703****Date:08/05/2015****Subject Name: Computer Graphics****Time:10.30AM-01.00PM****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.

- Q.1** (a) Derive all formulas for Bresenham line drawing algorithm. Write a function Bresenhamline(x1, y1, x2, y2, type) so it draws line with specified type. If type=0, solid line, type=1 dashed line and type=2 dotted line **07**
- (b) Derive all formulas for mid-point circle drawing algorithm. Apply algorithm and find out points for circle with radius 8 and centre (0,0) for one octant only **07**
- Q.2** (a) Briefly explain different methods to generate thick lines. Discuss merits and demerits of each method. **07**
- (b) What is frame buffer? How long would it take to load a 640 by 480 frame buffer with 12 bits per pixel if transfer rate is 1Mbps? What is the size of frame buffer? How many colors it support? **07**
- OR**
- (b) Briefly explain scan line polygon filling algorithm. Explain the fields of edge table and criteria for adding and removing edge to active edge table. **07**
- Q.3** (a) Briefly explain NLN line clipping algorithm. What are the advantages of NLN over Cohen Sutherland line clipping algorithm **07**
- (b) Prove that successive rotation is additive and commutative **07**
- OR**
- Q.3** (a) Briefly explain Cyrus Beuker line clipping algorithm. Compare Cyrus Beuker and Liang-Basky line clipping algorithm **07**
- (b) Determine the transformation matrix which reflects given object about diagonal  $y=x$  **07**
- Q.4** (a) Consider square with left-bottom corner at (2, 2) and right-top corner at (6, 6). Find out the transformation matrix which makes its size half such that its centre remains same. **07**
- (b) Define polygon mesh. Briefly explain different methods used to represent polygon mesh with example **07**
- OR**
- Q.4** (a) Consider a triangle with vertices A(1,1), B(5,2) and C(3,4). Find out the transformation matrix which rotates given triangle about point C (3,4) by an angle 30 degrees clockwise. Also find rotated triangle. **07**
- (b) Compare perspective and parallel projection. Briefly explain different types of parallel projections **07**
- Q.5** (a) Classify the visible surface determination algorithm. Briefly explain z-buffer visible surface determination algorithm **07**
- (b) Briefly explain diffuse and specular reflection. **07**

**OR**

- Q.5** (a) Briefly explain different techniques to make visible surface determination algorithm more effective. Briefly explain back face culling algorithm. **07**
- (b) (1) Briefly explain LCD and LED display **04**  
(2) Briefly explain CMY color model **03**

\*\*\*\*\*