

GUJARAT TECHNOLOGICAL UNIVERSITY**BE - SEMESTER VI- • EXAMINATION – SUMMER 2015****Subject Code: 160703****Date: 08/05/2015****Subject Name: Computer Graphics****Time: 10.30AM-01.00PM****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.

- Q.1** (a) Derive all formulas for Bresenham line drawing algorithm. Write a function Bresenhamline(x1, y1, x2, y2, type) so it draws line with specified type. If type=0, solid line, type=1 dashed line and type=2 dotted line **07**
- (b) Derive all formulas for mid-point circle drawing algorithm. Apply algorithm and find out points for circle with radius 8 and centre (0,0) for one octant only **07**
- Q.2** (a) Briefly explain different methods to generate thick lines. Discuss merits and demerits of each method. **07**
- (b) What is frame buffer? How long would it take to load a 640 by 480 frame buffer with 12 bits per pixel if transfer rate is 1Mbps? What is the size of frame buffer? How many colors it support? **07**
- OR**
- (b) Briefly explain scan line polygon filling algorithm. Explain the fields of edge table and criteria for adding and removing edge to active edge table. **07**
- Q.3** (a) Briefly explain NLN line clipping algorithm. What are the advantages of NLN over Cohen Sutherland line clipping algorithm **07**
- (b) Prove that successive rotation is additive and commutative **07**
- OR**
- Q.3** (a) Briefly explain Cyrus Beck line clipping algorithm. Compare Cyrus Beck and Liang-Basky line clipping algorithm **07**
- (b) Determine the transformation matrix which reflects given object about diagonal $y=x$ **07**
- Q.4** (a) Consider square with left-bottom corner at (2, 2) and right-top corner at (6, 6). Find out the transformation matrix which makes its size half such that its centre remains same. **07**
- (b) Define polygon mesh. Briefly explain different methods used to represent polygon mesh with example **07**
- OR**
- Q.4** (a) Consider a triangle with vertices A(1,1), B(5,2) and C(3,4). Find out the transformation matrix which rotates given triangle about point C (3,4) by an angle 30° clockwise. Also find rotated triangle. **07**
- (b) Compare perspective and parallel projection. Briefly explain different types of parallel projections **07**
- Q.5** (a) Classify the visible surface determination algorithm. Briefly explain z-buffer visible surface determination algorithm **07**
- (b) Briefly explain diffuse and specular reflection. **07**

OR

Q.5	(a)	Briefly explain different techniques to make visible surface determination algorithm more effective. Briefly explain back face culling algorithm.	07
	(b)	(1) Briefly explain LCD and LED display	04
		(2) Briefly explain CMY color model	03
