## **GUJARAT TECHNOLOGICAL UNIVERSITY** BE - SEMESTER-VI • EXAMINATION – SUMMER • 2015

Subject Name: MECHATRONICS		Name: MECHATRONICS		
	tructio		70	
Q.1	(a) (b)	Explain the design process of a Mechatronic system. Explain solid-state devices, which can be used electronically to switch circuit	07 07	
Q.2	<b>(a)</b>	<ul><li>(i) Explain different types of control systems with suitable example.</li><li>(ii) Give full form of following acronyms: AVCS,CIM,CAM,FMS</li></ul>	03 04	
	<b>(b)</b>	Compare the hydraulic and pneumatic systems. OR	07	
	(b)	Describe the operation and construction of, (i) Variable displacement Vane pump (ii) Double acting Cylinder	07	
Q.3	(a) (b)	<ul><li>Explain Derivative control mode in details with diagram.</li><li>Describe the following:</li><li>(i) Potentiometer Displacement Sensor</li><li>(ii) Bimetallic strip</li></ul>	07 07	
Q.3	(a) (b)	<b>OR</b> Explain any one displacement sensor with neat sketch. Explain displacement measurement using capacitive transducer and using LVDT.	07 07	
Q.4	<b>(a)</b>	What is a load cell? Explain briefly the construction and working of strain gauge load cell.	07	
	(b)	Explain mechanical factors or aspects for motor selection in Mechatronics systems.	07	
Q.4	(a)	<b>OR</b> Explain Proportional control mode in details with diagram	07	
-	<b>(b)</b>	Explain single phase induction motor and its working.	07	
Q.5	(a) (b)	Explain Master and Jump controls in PLC.Explain following terms of Microprocessori) ALUii) Control unitiii) Registersiv) Program counterv) Memory address registervi) Accumulator	07 07	
Q.5	(a) (b)	<b>OR</b> Explain any two types of stepper motor with suitable diagram. With a neat sketch Explain the Basic structure of a Programmable Logic Controller.	07 07	

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