## GUJARAT TECHNOLOGICAL UNIVERSITY BE – SEMESTER – VI (NEW).EXAMINATION – WINTER 2016

	Subject Code: 2160910 Date: 26/10/2016		
]	lime	ect Name: Electrical Drives : 02:30 PM to 05:00 PM Total Marks: 70 ctions:	
	11511 UN	<ol> <li>Attempt all questions.</li> <li>Make suitable assumptions wherever necessary.</li> <li>Figures to the right indicate full marks.</li> </ol>	
Q.1	(a) (b)	0	07 07
Q.2	(a) (b)	Explain type-A and type-B chopper. Explain the analysis of the PWM half bridge inverter. <b>OR</b>	07 07
	<b>(b)</b>	Explain the sliding mode control method.	07
Q.3	(a) (b)	Explain the model referencing adaptive control (MARC) method. Explain the torque equation for D.C motor. <b>OR</b>	07 07
Q.3	(a) (b)	Explain the Dynamic model of DC motor drive. Explain speed torque characteristics of DC series motor, DC shunt motor ,and PMDC motor.	07 07
Q.4	(a) (b)	Different between VSI & CSI induction motor drives. Explain d-q model of induction motor. OR	07 07
Q.4	(a) (b)	Explain advantages & disadvantages of traction drives. Explain basic structure of solar and battery powered drives.	07 07
Q.5	(a) (b)	Explain speed torque conventions and multi quadrant operation of drives. Explain steady-state and transient stability of an electric drive. <b>OR</b>	07 07
Q.5	(a) (b)	Explain four quadrant chopper (Type-E chopper). Explain single phase semiconductor & half controlled converter.	07 07

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