

GUJARAT TECHNOLOGICAL UNIVERSITY**B. E. - SEMESTER – VII • EXAMINATION – WINTER 2012****Subject code: 172401****Date: 26/12/2012****Subject Name: Power Electronics systems & Modeling****Time: 10.30 am - 01.00 pm****Total Marks: 70****Instructions:**

1. Attempt any five questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Notations / symbols used have their usual meanings.

- Q.1** (a) What is a Transfer Matrix & how it is obtained from state-space equations. **07**
 (b) Develop State-space model of the Buck-Boost converter. **07**

- Q.2** (a) Derive the expression of duty cycle for boost converter with the help of capacitor charge second principle. **07**
 (b) Show that during transient period net change in inductor current over one switching period can be correctly predicted by use of average inductor voltage. **07**

OR

- (b) Obtain transfer function of separately excited DC shunt motor. **07**

- Q.3** (a) Normalize the differential equation given below with respect to a frequency of 10 Hz and derive the subsequent state-space model. **07**

$$\ddot{x} + a\dot{x} + bx = f(t).$$

The system parameters are $a=10, b=10000, f(t)=100\cos(20\pi t)$.

- (b) Derive small signal AC model for buck-boost converter. **07**

OR

- Q.3** (a) Explain the principle of inductor volt second balance and capacitor ampere second balance. **07**
 (b) How the review of bode plot is useful in analysis of converters ? **07**

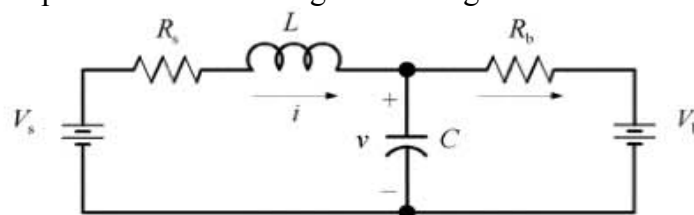
- Q.4** (a) What is small ripple approximation and how it is useful in converter analysis ? **07**
 (b) Derive transfer function of DC generator. **07**

OR

- Q.4** (a) Derive small signal linearized equation that describes variation in inductor current. **07**

- Q.4** (b) Obtain state space model for 1-phase bridge inverter **07**

- Q.5** (a) Derive state space for the following circuit diagram. **07**



- (b) Derive the equation for the selection of value of inductor for a boost converter so that the desired current ripple Δi_L is attained. **07**

OR

Q.5 (a) Find the state-space model of the second-order differential equation. **07**

$$\ddot{x} + a\dot{x} + bx = f(t).$$

(b) Find the complete state controllability of a converter whose state-space equation is given by **07**

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} u$$
