

GUJARAT TECHNOLOGICAL UNIVERSITY
ME - SEMESTER- I • EXAMINATION – SUMMER 2013

Subject Code: 712903N**Date: 13/06/2013****Subject Name: Digital Signal Controller****Time: 10:30 to 1:00****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.

Q.1 Do as directed : (02 marks each) **14**

- (i) State equation for a backward difference system. Will it be causal?
- (ii) Define DFT. State its two applications.
- (iii) Discuss significance of aliasing for sampling.
- (iv) Evaluate $(n-1)^* (n+1)$. Comments on result obtained.
- (v) Prove that $(n) = u(n) \circ u(n-1)$.
- (vi) State relation between Z-transform and DFT.
- (vii) Sketch various tolerance limits to approximate an ideal low pass filter.

Q.2 (a) Draw and explain the block diagram of basic generic hardware architecture for a signal processor. **07**

(b) Discuss discrete time processing of continuous time signals. **07**

OR

(b) Explain the changing of the sampling rate using discrete time processing. **07**

Q.3 (a) Determine the impulse response for the cascade of two LTI systems having impulse response : $h_1(n) = (1/2)^n u(n)$ and $h_2(n) = (1/4)^n u(n)$ **07**

(b) Determine the response of the system $y(n) = 5/6 y(n-1) - 1/6 y(n-2) + x(n)$ to the input signal $x(n) = (n) - 1/3 (n-1)$. **07**

OR

Q.3 (a) Write short note on: Hilbert Transform. **07**

(b) An LTI system is characterized by the difference equation $x(n-2] - 9x(n-1) + 18x(n) = 0$ with initial conditions $x(-1) = 1$ and $x(-2) = 9$. Find $x(n)$ by using z-transform and state the properties of z-transform used in calculation. **07**

Q.4 (a) Obtain the parallel-form structure of the given $H(z)$ for first-order and second order systems. **07**

$$H(z) = \frac{(1 + 2z^{-1} + z^{-2})}{(1 - 0.75z^{-1} + 0.125z^{-2})}$$

(b) For linear phase FIR filters, how constant group and phase delay is achieved? Enlist design techniques for the same. **07**

OR

- Q.4 (a)** Discuss (i) All-pass systems and (ii) Minimum phase system. **07**
- Q.4 (b)** Obtain impulse response of a digital filter to correspond to an analog filter with impulse response $h(t) = 0.5 e^{-2t}$ and with a sampling rate of 0.1kHz using impulse invariant method only. **07**
- Q.5 (a)** For $x(n) = (1, 1, -1, -1)$ use 4-point DIT, algorithm for FFT and cross check the result using DFT. **08**
- (b)** An LTI system is described with the following difference equation $y(n) = a y(n-1) + b x(n)$ for $0 < a < 1$ and $0 < b < 1$. Determine the magnitude and phase of the frequency response of the system. **06**

OR

- Q.5 (a)** Perform the Circular Convolution of the two sequences $x_1(n) = \{2, 1, 2, 1\}$ and $x_2(n) = \{1, 2, 3, 4\}$ **08**
- (b)** (i) Compare FIR filter with IIR filter in tabular form. **06**
(ii) Compare linear and circular convolution.
