Seat N	lo.:	Enrolment No	
		GUJARAT TECHNOLOGICAL UNIVERSITY M. E SEMESTER – II • EXAMINATION – SUMMER • 2014	
Subj	ect c	ode: 1724106 Date: 23-06-20	14
Subject Name: Image Matching and Registration Fime: 02:30 pm - 05:00 pm Total Marks: 70			n
Instru			U
	1. 2. 1	Attempt all questions.  Make suitable assumptions wherever necessary.  Figures to the right indicate full marks.	
Q.1	(a)	Define image registration. Classify various image registration approaches.	07
	<b>(b)</b>	Discuss the stereo vision system using block diagram.	07
Q.2	(a) (b)	Explain the steps for generalized image registration process. Discuss the Marrøs theory for computer vision.	07 07
	(b)	<b>OR</b> Define and explain the terms: multi-sensor, multi-view, multi-temporal, multi-resolution.	07
		muiti-resolution.	
Q.3	(a)	Explain how area based image registration works?	07
	(b)	Compare area based and feature base image registration process.  OR	07
Q.3	(a) (b)	Discuss Fourier transform based image registration process. How the image registration process is evaluated using various performance parameters?	07 07
Q.4	(a) (b)	Discuss similarity geometric transformation with necessary mathematical equations.  If an image is translated in x-direction by 25 pixels, translated in y direction by 20 pixels and then after rotated by 18 degree. For a pixel with coordinates (30, 40) what will be the new coordinates? How the projective and affine transform differs?	07
	(0)	OR	07
Q.4	(a) (b)	Write a short note on multi-quadratic transformation.  Discuss the comparison of bilinear and interpolation and nearest neighbor re-sampling methods.	07 07
Q.5	(a)	Discuss the non-parametric technique for image matching.	07
	(b)	Explain any one algorithm for line matching used for image registration.  OR	07
Q.5	(a)	List and discuss the challenges in image registration process for satellite images.	07
	<b>(b)</b>	Define and explain chamfer matching.	<b>07</b>

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