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GUJARAT TECHNOLOGICAL UNIVERSITY M. E. - SEMESTER – I • EXAMINATION – SUMMER • 2014

Subject code: 710802N Date: 17-06-2014 **Subject Name: Computer Aided Machine Design** Time: 02:30 pm - 05:00 pm **Total Marks: 70 Instructions:** 1. Attempt all questions. 2. Make suitable assumptions wherever necessary. 3. Figures to the right indicate full mark. **07** 0.1 (a) Explain the role of computer graphics in modeling and simulation of design. **(b)** Explain working significances of virtual design and testing softwares. 07 **Q.2** Determine the pixels for a straight line connecting two points (2, 7) and (15, 10) (a) **07** using DDA algorithm. **(b)** Explain Bresenhamøs algorithm for Ellipse. 07 **(b)** Write a C program of Bresenhamøs algorithm for circle. 07 **Q.3** (a) Compute the Bezier curve for a set of control points is given by 07 $P_0 = (4, 4), P_1 = (6, 8), P_2 = (8, 9) \text{ and } P_3 = (10, 3).$ **(b)** Explain parametric representation of surface using 16 points form of Matrix. 07 The corners of wedge-shaped block are A(0, 0, 2), B(0, 0, 3), C(0, 2, 3), D(0, 2, 3)**Q.3** 07 2), E(1, 2, 2) and F(1, 2, 3), and the reflection plane passes through the yaxis at 45° between (x) and z-axis. Determine the reflection of the wedge. **(b)** Explain the characteristics of blending functions and twist vectors for surface. 07 **Q.4** (a) Explain feature based modeling techniques with its significances. 07 (b) Derive the generalized 2-D transformation matrix for a reflection about an 07 arbitrary line y = mx + c with usual notations. Explain IGES, STL and DXF file format of graphics interface. 0.4 07 What is spline? Explain the properties of normalized B-splines. (b) **07** Write a C program for rigid coupling design with usual formulae and notations. 07 **Q.5** (a) (b) Write a C program for Spring Design with usual formulae and notations. 07 Explain the Johnson
øs method of Optimum design. 0.5 (a) 07 Prove that optimization in power transmitted by a spur gear occurs when 07 tangential load is equal to dynamic load under the failure of scoring. Assume dynamic load directly proportional to pinion speed.
