Seat No.: _____

GUJARAT TECHNOLOGICAL UNIVERSITY ME – SEMESTER II– EXAMINATION – WINTER - 2016

Subject Code: 2722710

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Subject Name: Neuro Computing and Applications
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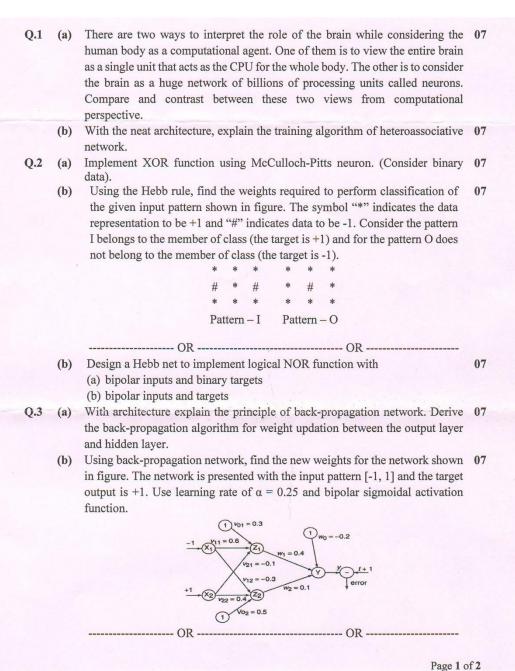
Time: 2:30 pm to 5:00 pm

Total Marks: 70

Date: 21/11/2016

Instructions:

- 1. Attempt all questions.
- 2. Make suitable assumptions wherever necessary.
- 3. Figures to the right indicate full marks



- Q.3 (a) Draw the architecture of ADALINE and MADALINE net. Differentiate two 07 training algorithms for MADALINE, *viz.*, MR-I and MR-II.
 - (b) Implement OR function with bipolar inputs and targets using ADALINE net. 07 Consider the initial weights are $b = w_1 = w_2 = 0.1$, and the learning rate is set to $\eta = 0.1$. Show the performance (i.e. MSE) of the ADALINE net at least for two epochs of learning.
- Q.4 (a) With neat architecture, explain the training algorithm of Kohonen self- 07 organizing feature maps.
 - (b) Construct and test an Learning Vector Quantization (LVQ) net with five 07 vectors assigned to two classes. The given vectors along with the classes are as shown in table.

| | Ţ | /ed | cto | Class | |
|---|---|-----|-----|-------|---|
| [| 0 | 0 | 1 | 1] | 1 |
| [| 1 | 0 | 0 | 0] | 2 |
| [| 0 | 0 | 0 | 1] | 2 |
| [| 1 | 1 | 0 | 0] | 1 |
| [| 0 | 1 | 1 | 0] | 1 |

Q.4 (a) What is the basic concept behind Adaptive Resonance Theory (ART)? Sketch 07 the architecture of ART 1 network and discuss its training algorithm.

(b) With neat architecture, explain each step of flowchart for training algorithm of 07 Radial Basis Function (RBF) network. Further, list out major differences between RBF and back-propagation multi-layer network.

| Q.5 | (a) | Discuss how a Support Vector Machine (SVM) can be used to solve an M-ary pattern classification problem, where M=2. | | | | |
|-----|-----|---|----|--|--|--|
| | (b) | Write notes on application of neural networks in pattern recognition. | 07 | | | |
| Q.5 | (a) | Briefly explain NARX model for recurrent network architecture. | 07 | | | |
| | (b) | Discuss application of neural networks in robotics. | 07 | | | |
